FAND TES

INSTRUCTION MANUAL 4.1



Kotouc Gearboxes WORKSHOP MANUAL



DESCRIPTION OF FUNCTIONS OF THE ALL WHEEL DRIVE TRACTION CONTROL SYSTEM FOR NISSAN GTR

The All Wheel Drive Traction Control System (AWD TCS) is very important for controlling vehicles at a high speed and in difficult driving conditions. The AWD TCS is both a road and race system that will enable the Nissan GTR to drive more aggressively without the loss of traction on the wheels.

The AWD TCS is a revolutionary system that utilises all of the available data and sensors in the GTR to adjust the torque split between front and rear wheels to deliver maximum traction!

In high horsepower GTRs, being able to deliver all the power to the wheels while maintaining full traction is the biggest challenge to tuners. Additionally, handling suffers.

The AWD TCS puts the car GTR back on rails! It is fast reacting to minimise slippage and the mapping allows the braking, cornering and acceleration of the GTR all to be improved significantly.

The AWD TCS finally allows you to utilise the GTR's maximum potential with fully customisable maps for all conditions, which no other controller on the market can deliver!

MAIN ADVANTAGES

- 1. Storing capacity of up to 4 created maps right in the AWD TCS unit. Switching over by the toggle button on the vehicle dashboard. Active maps are between 1-4.
- 2. A possibility to create your own map files.
- 3. Maximum torque split available between front and rear wheels of 50/50.
- 4. Burnout mode with differential deavtivation.
- 5. Plug and play
- 6. No wires or any plastic boxes showing in the interior

GTR AWD TCS Contents

- 1. Installation and setup
- 2. Selection of maps
- 3. Burnout mode
- 4. Map Tab explained
- 5. Creating a new map
- 6. Password protection of maps
- 7. Headers variable
- 8. Wheel vs Angle values
- 9. Diagnostics
- 10. Setup tab explained
- 11. Brake Sensitivity
- 12. Memory ACD Maps
- 13.Launch control
- 14. Upload of upgraded firmware
- 15.Datalogger

1. INSTALLATION and SETUP

The GTR AWD TCS does not require specialist setup. There is no setup procedure necessary for compatablity of the AWD TCS unit. It is only necessary upon installation to ensure the ignition and engine is switched off.

Maps can be selected by activating the Torque split screen on the dash.

To install the unit, locate the original ECU under the front passengers seat. It is hidden in the floor under the carpet.

Replace the OEM unit with the Kotouc Gearboxes GTR AWD TCS unit.

2. SELCTION OF MAPS

CHANGING OF ACTIVE MAP

It is necessary to have the TORQUE SPLIT graph active on the dash.

To change the map, select the left toggle switch DOWN, UP, DOWN, UP. This combination must be done within 2 seconds. This will activate the change map mode.



After the torque split graph will start flashing. The maps are set up as follows:

Map 1 = Torque split 25% Map 2 = Torque split 50% Map 3 = Torque split 75% Map 4 = Torque split 100%

Each press of the left toggle switch down will result in the next map being selected.

Once the desired map has been selected, the map will be saved after a few seconds and the torque split will stop flashing.

Note: Maps do not have a constant 25, 50, 75 or 100% torque split between the front and rear wheels. Torque split graph only indicates which map is selected.

3. BURNOUT MODE

It is possible to completely disable the center differential and drive only the rear wheels. To do this, a map can be created and saved where all values are O (zero). Then select this map on the dash for 100% rear wheel drive.

Alternatively, burnout mode is active when the change map mode is active. Before any map has been changed, the differential is switched off so the GTR will be in full rear wheel drive only to make a short burnout. Once the change map mode time elapses, the differential will again default to the previous map that was selected. (check firmware version for this functionality)

Tick active burnout mode Set ACTIVE time (seconds)

WD Nissan GTR V2	- 🗆 X
Exit Open Save New Read Verify Program Clear Logger Port Info	
Maps Setup Power modulation Bum out mode ①① Coil power on maps [½] Ignition ①① Coil power on start program [½] ①① Time [9] Tables view ①① Time [9] Tables view □② Coil power on start program [½] □③ Coil power on start program [½] □③ Time [9] □③ Coil power on start program [½] □③ Time [9] □③ Coil power on start program [½] □④ Time [9] □③ Coil power on start program [½] □④ Time [9] □③ Coil power on start program [½] □④ Time [9] □● Biocation pointers from MCU □ Each wheel speed □ Lock map header speed □ Axis slip □ Show miles per hour □ Hat □ Hat □ Hat	Map - 1
	G-sensor
0%	0%
St. angle = 0 [']	0%
Uploader 0% Votage	0%
	Start Record

4. MAP TAB EXPLAINED

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mape	Jeiu	h														Map - 1
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20	0	0	0	0	0	0	0	0	0	0	0	0	0	0 0	0	>3 >5 >7 >9 >11 >13 >15 >17 >19 >21 Bedra = 0.1%
30	0	0	0	0	0	0	0	0	0	0	0	0	0	0 0	0	
40	0	0	0	0	0	0	0	0	0	0	0	0	0	0 0	0	If TPS > [%] 30 ♣ If Speed > [km/h] 50 ♣
50	0	0	0	0	0	0	0	0	0	0	0	0	0	0 0	0	
60	0	0	0	0	0	0	0	0	0	0	0	0	0	0 0	0	Low speed condition Active B0
/0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 0	0	>3 >5 >7 >9 >11 >13 >15 >17 >19 >21 0 0 0 0 0 0 0 0 0 0 0 0 0 0 Park Foot
90	0	0	0	0	0	0	0	0	0	0	0	0	0	0 0	0	
100	0	0	0	0	0	0	0	0	0	0	0	0	0	0 0	0	# TPS > [%] 30
																Slip axle [%] L0 R0
Left f	oot bra	aking						Speed	[km/h]					Active	Front Active G-sensor
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Brake	e [%]	Г	Rear	com	ensati	ion	9	Speed	km/h	1				Г	Active	>5 >10 >15 >20 >25 >30 >35 >40 >45 >50 0%
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40	0	0	0	0	0	0	0	0	0	0	0	0	0	0 0	0	Start program
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100	•	•	•	•	•	•	•	•	•	•	<u> </u>		•		100 4	Memory AWD
Мар	user na	ame (m	ax 20 c	harad	cters)						В	rake s	ensitivit	y [%]	100 -	Map - 1 V Lock/Unlock 0% 0%
new							Ser	ial nur	n selec	t:All						Voltage: 0,0 V
																Start Record
ECU disc	onne	cted														

Top Left: Main mapping table Speed kmph x TPS%

This table is used to input the primary values for lock of the center differential

Middle Left: Left Foot braking Speed kmph x Foot Brake x TPS

This table is used as a replacement to the main mapping table if both the TPS and Foot Brake Pedal sensor is active. The TPS>% condition field can be toggled to adjust the point of activation of the table.

Bottom Left: Main brake table Speed kmph x Foot Brake%

This table is used as a replacement to the main mapping table and helps fine tune the adjustment of lock based on the pressure applied to the brake pedal. The sensitivity of the brake pedal can be adjusted to suit. 100% is maximum braking pressure on a dry tarmac road.

Top Right: Compensation tables Steering Angle, Slip Axle These tables are used in addition to the main mapping table. Steering angle and slip axle help fine tune the lock on the center differential.

Bottom right: Start program and active map info There is a start program feature for launching from a standing start.

Far Right: Live Graphical AWD TCS interface

After the AWD TCS unit is connected to a notebook, the data may be read when driving - graphic representation of the current state of the vehicle (very helpful for completing the notion of how individual sensors work and how they influence the clamp of the centre differential in percentage).

Live Graphical AWD TCS interface

- 1. TPS indication of the gas pedal position in the range of O-100%
- 2. SPEED indication of the speed of the vehicle (in km/hour)
- 3. BRAKE indication of the pressure on the brake
- 4. PARK signals the hand brake engagement
- 5. FOOT signals the use of brake pedal (brake light sensor)
- 6. G- sensor shows the value of longitudinal and lateral overload
- 7. SLIP indication shows the slip of individual wheels (0-100%). If you click the AXIS view field, the slip of the fore axle as against the rear axle will be graphically represented
- 8. % indication shows the level of clamp of the centre differential in %



5. CREATING A NEW MAP

It is necessary to press NEW to create a new map.



After this, you can enter new values to the mapping table. If you wish to edit maps, only overtype the previous data to program.

The SAVE button will allow you to save that map to your PC hard drive.

The PROGRAM button will save the map onto the selected map position in the memory AWD field.

You can create an unlitmied amount of maps and save them to your PC. Maximum 4 maps can be saved into the controller on any position desirable.

G. PASSWORD PROTECTION OF MAPS

To protect a map file from being viewed, check the "LOCK / UNLOCK" box

# AWD Nissan GTR V2	– 🗆 X
Exit Open Save New Read Verify Program Clear Logger Port Info	
Maps Setup	Man - 1
TPS [%] Speed [km/h]	TPS = 0 [%]
20 40 60 80 100 120 140 160 180 200 220 240 260 280 300 > Steering angle []	Speed = 0 km/bl
10 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	
20 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Brake = 0 [%]
30 0	
40 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	+
50 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	
60 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	e B0
70 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	
80 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Park
90 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	
Slip axle [%]	
Left foot braking Speed [km/h] Active Front Activ	G-sensor
20 40 60 80 100 120 140 160 180 200 220 240 260 280 300 > 55 >10 >15 >20 >25 >30 >35 >40 >45 >5	D
If TPS > [%] 15 ⊕	
Rear Activ	A0 A0
Brake [%] Rear compensation Speed [km/h] Active >5 >10 >15 >20 >25 >30 >35 >40 >45 >55	0 0%
20 40 60 80 100 120 140 160 180 200 220 240 260 280 300 > 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	
20 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	
40 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	
60 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	ve St. angle = 0 [°] 0%
100 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	
Map user name (max 20 characters) Brake sensitivity [%] 100 🔿	k 0%
new Serial num select : All	Vehace: 0.0 V
	volidge. 0,0 v
T-	Start Record
ECU disconnected	

Password is of your choosing as a 4 digit pin code only.

Enter p	assword ×										
Map read enable (PIN):											
ECU serial num	iber: 0 👟										
ОК	Cancel										

NOTE: The password protection is associated to the map. To lock all maps, you must password protect each individually. Changes are saved only by the Program button. It is possible to add a serial number to the map so the map will run on only the corressponding GTR unit.

1. HEADERS VARIABLE

It is possible to amend the header parameters so the mapping of the unit can be either more condensed or expanded. The headers are on the main mapping table, left foot braking table and also the brake table.



They can be changed independently or together. Use the toggle box on the setup tab "Lock map header speed" to adjut the settings. Always program your changes

AWD Nissan GTR V2		– ×
Exit Open Save New Read Verify Program	Clear Logger Port Info	
Exit Open Save New Read Verify Program Maps Setup Power modulation Burn out mode ①●● Coll power on maps [½] ①● Active ①●● Coll power on start program [½] ①● Tables view Blocation pointers from MCU Blocation pointers from MCU Blocation pointers from MCU Lock map header speed Show miles per hour Logger files directory	Clear Logger Port Info Monitor 2	Map - 1 TPS = 0 [%] Speed = 0 [km/h] Brake = 0 [%] DA 0 V *C B0 Park Foot G-sensor R0
		0% A0 0%
	Uplo	ader 0% 0% 0%
·		Start Record

Right click once on the parameter cell to adjust values. The cell will appeal yellow.

If a mistic is made, the system will not allow you to save the map.

NOTE: Any changes you make, you must press the PROGRAM button to save your changes to the ACD computer. If not, changes will be lost. Alternatively, pressing save will save the map file to an alternative medium.

The mapping table is active only in the range of the conditioning parameters TPS and speed.

8. WHEEL ANGLE vs STEERING ANGLE values

The steering angle mapping table has is split into a high speed and low speed condition. Both have conditioning of speed and TPS. This will fine tune the car for better handling around tight corners and long high speed cornering.

There are 2 ways of analysing the steering and cornering of the car. That is by Wheel angle and steering angle. WHEEL ANGLE relates to the steering wheel turn and STEERING ANGLE relates to the angle (°) of the front tyres.

Parameters WHEEL ANGLE: max scores L420 : R420 (left and right) STEERING ANGLE: max scores L30 : R30 (left and right)

Wheel angle max values determined from GEMS dash + / - 420.



9. DIAGNOSTICS

Should there be any errors in the system, it is possible to diagnose the issue with the MONITOR 2 screen



Simply connect the software and quote your Serial number and FW code found in the status bar or the software and a technik will be able to assist.

10. SETUP TAB EXPLAINED

The setup page controls a number of important features in in GTR AWD TCS unit. These settings are saved to the unit, not the individual maps.

AWD Nissan GTR V2			- 🗆 X
Exit Open Save New Read	Verify Program Clear Logger Port	Info	
Power modulation Image: Coll power on maps [%] Image: Coll power on start program [%] <th>Burn out mode</th> <th>Monitor 2 Ignition Burn out mode Coll current: 0.00 A Layer voltage: 0.0 V Gearbox temp: 0 °C Gearbox SW: 0</th> <th>Map - 1 TPS = 0 [%] Speed = 0 [mph] Brake = 0 [%] B0 Park Foot C0 Geensor 0% St. angle = 0 ['] 0%</th>	Burn out mode	Monitor 2 Ignition Burn out mode Coll current: 0.00 A Layer voltage: 0.0 V Gearbox temp: 0 °C Gearbox SW: 0	Map - 1 TPS = 0 [%] Speed = 0 [mph] Brake = 0 [%] B0 Park Foot C0 Geensor 0% St. angle = 0 ['] 0%
		Uploader	0% Voltage: 0,0 V
			Start Record
ECU disconnected			

POWER MODULATION

Coil power on maps%: Refers to the amount of power that the coil will operate with. 60% is the standard default point which is satisfactory for a car of 800HP. It can be adjusted as seen fit. The correct setting is when the power level of the coil turns the differential without any slipping.

Coil on start program%: Refers to the power to the coil when the lunch control semence is activated

TABLES VIEW

Blockation pointers from MCU: turn off indication lighton maps. Lock map header speed: Independent or combined toggling of header changes Show miles per hour: Toggle between MPH and KMPH

BURNOUT MODE See charter 3

MONITOR VIEW

Each wheel speed: Toggle on live data wheel speed / % slip Axis slip:Toggle on live data individual wheel or axis slip Monitor frequency refresh: Record speed of datalogger

MONITOR 2 Quick view systém analysis

UPLOADER BUTTON

This is used to upload inside the ACD computer new versions of firmware.

LOGGER FILES DIRECTORY

Upload your saved datterlogger files here to playback for analysis

11. BRAKE SENSITIVITY

It is possible to change the sensitivity of the brake pedal to suit your car. The brake sensitivity feature is only associated with the main brake table. The level of 100% is the base value for changes to be calculated. Base value of 100% is determined from the maximum stopping power of the GTR on dry tarmac conditions during testing.

The brake sensitivity has a value range from 50%-150%. Should your car have a higher or lower level of grip, then you can adjust the sensitivity accordingly.

For example: Any changes to the setting of the brake sensitivity, the system will recalculate so it will be max 100% brake percentage on the brake mapping table.

NOTE: The TPS % toggle box is related to the left foot brake table, not the main brake map table.

NOTE: Brake sensitivity is programmed to the selected map only. Each map can have different brake sensitivity.

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U Exit	c	pen	H Save	Ne) ~	Re	ad	Verif	y Pro	1 gram	n Ci	ear	Logo	ć jer ∎	f Port	- Info	
Maps	Setu	p															Man - 1
TPS	[%]						Speed	[km/h	1								TPS = 0 [%]
	20	40	60 80	100	120	140	160	180	200	220	240	260	280 3	00 >		Steering angle ["]	Speed = 0 km/b]
10	0	0	0 0	0	0	0	0	0	0	0	0	0	0	0 0	1	High speed condition	Speed - 0 [kii/i]
20	0	0	0 0	0	0	0	0	0	0	0	0	0	0	0 0	1	>3 >5 >7 >9 >11 >13 >15 >17 >19 >21	Brake = 0 [%]
30	0	0	0 0	0	0	0	0	0	0	0	0	0	0	0 0		0 0 0 0 0 0 0 0 0 0	
40	0	0	0 0	0	0	0	0	0	0	0	0	0	0	0 0		If TPS > [%] 30 ♀ If Speed > [km/h] 50 ♀	
50	0	0	0 0	0	0	0	0	0	0	0	0	0	0	0 0			
60	0	0	0 0	0	0	0	0	0	0	0	0	0	0	0 0		Low speed condition	BO
70	0	0	0 0	0	0	0	0	0	0	0	0	0	0	0 0		>3 >5 >7 >9 >11 >13 >15 >17 >19 >21	Dest. Fast
80	0	0	0 0	0	0	0	0	0	0	0	0	0	0	0 0		0 0 0 0 0 0 0 0 0 0	Pot
90	0	0	0 0	0	0	0	0	0	0	0	0	0	0	0 0		If TPS > [%] 30	
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Left f	oot bra	aking					Speed	[km/h						Activ	8	Front Active	G-sensor
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												f TPS	>[%]	15 🌲		B	
		_	_													Rear Active	AU
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40	0	0	0 0	0	0	0	0	0	0	0	0	0	0	0 0			St angle = 0.1°1
60	0	0	0 0	0	0	0	0	0	0	0	0	0	0	0 0		Speed < [km/h] 40	or. angro = 0 [] 0%
80	0	0	0 0	0	0	0	0	0	0	0	0	0	0	0 0			
100	0	0	0 0	0	0	0	0	Ë							1	Temory AWD	
Man	userna	ame (m	ax 20 cha	racters						Br	rake s	ensitivit	ty [%]	100 🌲			
new	cicor ris	anno (n	ax 20 6/10	- docoro	, 	See	rial num	e e le r	+ · All								0%
						56		00100	A . / W								Voltage: 0,0 V
																	Start Record
ECIL die		cted															
200 0150	.onne	ucu															

Compensation Check Box The "Compensation" check box assoiated with the main brake table when ticked, will add into the diff lock the rear axle slippage % mapping values.



12. MEMORY AWD TCS MAPS

The AWD TCS has a possibility to run with 4 maps.

Map 1 – 25% Torque split level Map 2 – 50% Torque split level Map 3 – 15% Torque split level Map 4 – 100% Torque split level

Maps can be saved to a computer and loaded also to additional AWD TCS units. If any values are edited directly inside the AWD TCS unit, it is necessary to press the program button to save those changes.

✓ AWD Nissan GTR V2 - X													
🔯 📫 🛗 🗎 V 🏫 🖉 🛱 V 🚺													
Mans Satur													
	Map - 1												
IPS [%] Speed [km/h] Interview Interview Interview Interview Steering angle [*]													
10 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Speed = 0 [km/h]												
20 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Brake = 0.[%]												
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70 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Park Foot												
100 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0													
Left foot braking Speed [km/h] Active Front Artive	G-sensor												
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₩ TPS > [%]													
	AU												
Brake [%] Rear compensation Speed [km/h] Active 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0%												
40 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0													
60 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	St. angle = 0 [°]												
100 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0													
Brake sensitivity [2] 100													
Map user name (max 20 characters) Map -1 V Lo k/Unlock	0%												
	Voltage: 0,0 V												
	Start Record												
ECU disconnected													

Note: Maps do not have a constant 25, 50, 75 or 100% torque split between the front and rear wheels. Torque split percentage only indicates which map is selected.

13.LAUNCH CONTROL

The Launch control sequence is a special feature in the AWD TCS that will lock the differential at a user selected preset for maximum grip upon take off.

To activate the Launch conutrol, tick the startprogram active box. (Start program is saved on the map only, Each map is tuned individually).

Select the top speed that the start program will deactivate and set the amount of lock that the differential will have duing the launch phase.

Program any changes in the software.

The Launch control is active when the car is stationary (>5kmph) and TPS (throttle) is depressed 80% for approximately 0.5 seconds. The launch control will remain active for 10 seconds if the car remains stationary (>5kmph).

Once the car reaches the programmed speed, launch control sequence will end and revert to the main mapping table. It will also end if the brake is pressed or if the car is cornering.

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Evit	On	en Save	New	Read	Verify	Progra	m Cl		⇒ . Poger P		
Maps	Setun			TTC D C		, in a gree					
Maps TPS 10 20 30 40 50 60 70	Setup 20 4 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	40 60 80 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 100 120 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Spi 140 1 0 0 0 0 0 0 0	eed [km/h 60 180 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	200 220 0 0 0 0 0 0 0 0 0 0 0 0 0	240 0 0 0 0 0 0 0 0 0	260 280 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	300 > 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Steering angle ['] TPS Hgh speed condition Active >3 >5 >7 >9 >11 >13 >15 >17 >19 >21 0	B0
80 90 100	0 0 0	0 0 0 0 0 0 0 0 0	0 0 0 0 0 0	0 0 0	0 0 0 0 0 0	0 0 0 0 0 0	0 0 0	0 0 0 0 0 0	0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Park Foot
	20 4 0	40 60 80 0 0 0	0 100 120	140 1 0	60 180 0 0	200 220	0 240	260 280 0 0 ff TPS > [%]	300 > 0 0 15 €	Front Active >5 >10 >15 >20 >25 >30 >35 >40 >45 >50 0	A0
Brake 20 40	e [%] 20 4 0	Rear co 40 60 80 0 0 0 0 0 0	Impensation 100 120 0 0 0 0 0 0 0 0 0	Spo 140 1 0 0	eed [km/h 60 180 0 0 0 0	200 220 0 0 0 0	0 240 0 0	260 280 0 0 0 0	Active 300 > 0 0 0 0	>5 >10 >15 >20 >25 >30 >35 >40 >45 >50 0 0 0 0 0 0 0 0 0% Start program	0%
60 80 100 Map	0 0 0 user nam	0 0 0 0 0 0 0 0 0 ne (max 20 cha	0 0 0 0 0 0	0 0 0	0 0 0 0 0 0	0 0 0 0 0 0	0 0 0 Brake se	0 0 0 0 0 0 ensitivity [%]	0 0 0 0 0 0 100 €	Speed < [km/h] 40 🔄 Lock [%] 100 🔄 Active St. a	ngle = 0 ['] 0%
new ECU disc	connecte	ed] Serial	num selec	t : All					Voltage: 0.0 V Start Record

14. UPLOAD OF UPGRADED FIRMWARE

On the setup tab, click the "Uploader" button.

AWD Nissan GTR V2			- 🗆 X
Exit Open Save New Read V	/erify Program Clear Logger Port	Info	
Maps Setup Power modulation	Burn out mode	Monitor 2	Map - 1
0	☐ Active	Ignition Burn out mode	Speed = 0 [mph] Brake = 0 [%]
Tables view	Monitor view	Coil current: 0,00 A Layer voltage: 0,0 V	
Blocation pointers from MCU Lock map header speed Show miles per hour	Each wheel speed Axis slip H7 V Monitor frequency refresh	Gearbox temp: 0 °C Gearbox SW: 0	B0 Park Foot
Logger files directory			L0 G-sensor R0
			A0 0%
			St. angle = 0 [*] 0%
		Uplunder	0%
+		\ _	Start Record
ECU disconnected			:

Select the file sent by Kotouc Gearboxes .upg

🙏 Open		Court Sur	×		
Computer		Search EVOX	<u>ر</u>		
Organize 🔻 New folder			•		
Documents 🔺	Name	Date modified	Туре		
J Music	2012_01_10	10.1.2012 19:27	File folder		
Videor	퉬 EVO Xa	12.1.2012 19:24	File folder		
Videos	EvoX version 01_06.upg	12.1.2012 19:37	UPG File		
Homegroup Homegroup K Computer ACER (C:) DVD RW Drive (D KINGSTON (E:) K Webové servery v	11				
File <u>n</u> ar	ne: EvoX version 01_06.upg	Uploader files <u>O</u> pen	▼ Cancel		

15. DATALOGGER

The Kotouc Gearboxes GTR AWD TCS has a datalogger functionality when connected to your PC/Notebook via the communication cable.



To activate the datalogger, press START RECORD.All the sensors of the traction control systém will be recorded for playback.

Press STOP dogger when finished.

The frequency of record is via the Monitor Frequency Refresh rate located on the setup ta band explained in section 10.

To play a recorded log file, select the LOGGER drop down box and choose START LOGGER FROM FILE.

When the dialogue box opens, choose the .log file you wish to review.

🖛 AW	D Niss	an GTR	V2																- 🗆 🗙
Exit	C	nen (H	N	lew		Rez	e d	Verif	v Pr	1 ogran		ear (⇒ aaer	• p		Logger pl	aying
Maps	Setu	n													S	tart lo	gger from file		Man 4
	,	-												ъ	E	nd log	ger from file	TPS = 30 [%]	Map - 1
IPS	10	24	26	10 0	0	70	04	opeed	[mph]	120	100	145	167	10	s	how q	raphs		
10	12	10	10	10 1	0	10	10	10	100	120	10	140	10	10	10	10	High speed condition Active	Speed = 0 [mph]	
20	20	20	20	20 2	20	20	20	20	20	20	20	20	20	20	20	20	>1 >3 >5 >7 >9 >11 >13 >15 >17 >19	Brake = 0.1%1	
30	30	30	30	30 3	80	30	30	30	30	30	30	30	30	30	30	30	1 -2 -3 4 -5 -6 -7 -8 -9 -10	brake = 0 [%]	
40	40	40	40	40 4	10	40	40	40	40	40	40	40	40	40	40	40	If TPS > [%] 30 ♣ If Speed > [km/h] 50 ♣		
50	50	50	50	50 5	60	50	50	50	50	50	50	50	50	50	50	50			
60	60	60	60	50 E	60	60	60	60	60	60	60	60	60	60	60	60	Low speed condition		B0
/0	/0	/0	/0	/0 /	0	/0	/0 00	/0	/0	/0	/0	/0	/0	/0	/0	/0	>1 >3 >5 >7 >9 >11 >13 >15 >17 >19	Park	Foot
90	90	90	90	30 0	0	90	90	90	90	90	90	90	90	90	90	90			
100	100	100 1	100 1	00 1	00	100	100	100	100	100	100	100	100	100	100	100	lf TPS > [%] 29		
																	Slip axle [%]	L0	
Left	oot bra	aking					9	Speed	[mph]						\checkmark	Active	Front Active		G-sensor
	6	12	18	24 3	80	36	42	48	54	60	66	72	78	84	90	>	>5 >10 >15 >20 >25 >30 >40 >50 >70 >90		
	5	10	15	20 2	25	30	35	40	45	50	55	60	65	70	75	80	10 20 15 40 50 60 70 80 90 100		
													IF TPS	5 > [%		60 ≑	Bear Z Active		A0
Deals	- 1%1		Pear				0	Second	[mala]							A	>1 >3 >5 >7 >9 >11 >13 >15 >17 >19		,
Drak	6	12	18		isauc	36	12	18	[mpn] 54	60	66	72	78	8/	90	Active	-1 -2 -3 -4 -5 -6 -7 -8 -9 -10	0%	0%
20	1	2	3	0	5	6	7	8	9	10	11	12	13	14	15	30			
40	17	18	19	20 2	21	22	23	0	25	26	27	28	29	30	31	32	Start program		
60	33	34	35	36	0	38	39	40	41	42	43	44	45	46	47	48	Speed < [km/h] 50	St. angle = 0 [°]	0%
80	49	50	0	52 5	i3	54	55	56	57	58	59	60	61	62	63	64			
100	0	66	67	0 6	9	70	71	0	73	0	75	76	77	78	79	80	Memory AWD		
Мар	user na	ame (ma	x 20 cl	naracte	ers)						В	rake s	ensitiv	ity [%] [1	00 🗘	Mar 1 Jock / Joleck	0*	
testir	g map	1					Seri	ial nur	n selei	ct:All							Map - 1	0%	0%
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Mod I:	NGTR	-00000	01	Firmw	are:	4.120)			File	: NG	rr-00	00000	1 - D	ate 2	019_0	3_05 - Time 01_34_27 - Total Rec 00_01_02.log	05-03-2019 - 01:34	27 - Logger time : 00:00:00
	1																		

When a log is open, you can choose to PLAY the fileat various speeds from the drop down box.

Alternatively, you can drag the play bar from left to right.

Time stamp and record information are located in the status bar.

To revert back to the active maps, choose LOGGER and END LOGGER FROM FILE.

